TRIODRIVE C / MIDIDRIVE C

Modular Multi-Axis Servo System for Any Type of Servo Motors Servo Power Modules for Direct Mains Connection Motion Control Modules for Coordinated Axis Motion



MidiDrive C (3×400/480 V AC) Servo Power Modules Motion Control Modules as 19" Modules in the SYSTEM-90E Controller

TrioDrive C (230 V AC) Servo Power Modules

Main Characteristics

- High-quality drive system for coordinated multi-axis motion
- Modular construction with perfectly matching components
- · Minimum variety of components

Servo power modules

- For the flexible control of different motor types, e. g. AC or DC servo motors, linear motors, 2- and 3-phase servo motors from 1 to 50 pole pairs
- Compact design for direct mains connection to 230 V AC / 3 × 400/480 V AC
- For motor powers from 0.1 to approx. 11 kW

Motion control modules

- With integrated digital position and speed control for highest accuracy
- High flexibility and dynamics due to multitasking operation and minimum response times
- Suitable for various position sensor types (resolvers, incremental encoders, absolute encoders, etc.)

Applications

Particularly useful for coordinated multi-axis applications, e. g. in

- · handling and assembly systems or
- · pick-and-place applications

Main Characteristics

Eight power classes

| Servo Po | Servo Motors | | | |
|-------------|----------------|-----------------------|--------------|--|
| Family | I _N | I_N U_{Z_k} P_N | | |
| TrioDrive C | 2 A | 320 V | up to 0.6 kW | |
| | 4 A | 320 V | up to 1.2 kW | |
| | 6 A | 320 V | up to 1.8 kW | |
| MidiDrive C | 2 A | 560 V | up to 1.1 kW | |
| | 4 A | 560 V | up to 2.2 kW | |
| | 8 A | 560 V | up to 4.5 kW | |
| | 12 A | 560 V | up to 6.6 kW | |
| | 20 A | 560 V | up to 11 kW | |

Characteristics of the multi-axis servo system

- High-quality drive system for coordinated multiaxis motion
- Optimized motion with defined acceleration and jerk control
- Modular design with perfectly matching components
- · Minimum variety of components
- Digital system parameterization, programming, and monitoring (drives and motion control) with only one software
- For applications with different motor types such as
 - AC or DC servo motors
 - linear motors, solenoid motors
 - direct drives, torque motors
 - 2- and 3-phase motors
 - 1 to 50 pole pairs
- · Flexible position sensing
- Functions such as point-to-point positioning, axis interpolation, etc. available via the SYSTEM-90E Promicon Systems controller
- Integral system diagnosis with alarms and log file recording
- Integration into higher-level controller systems via Profibus, Interbus, OPC, or pNET (RS232)

Characteristics of the servo power modules

- · For the flexible control of different motor types
- Suitable for servo motors by ESR Pollmeier or other manufacturers
- For motor powers from 0.1 to approx. 11 kW

- Compact design for direct mains connection:
 - TrioDrive C to 230 V AC
 - MidiDrive C to 3 × 400/480 V AC
- Wide-range inputs, also suitable for lower connection voltages
- Simple connection to the motion control module via standard RJ 45 cable
- Several devices can be mounted directly next to each other (without lateral gap)
- Clearly arranged wiring as all connectors can be plugged in at the front
- High performance at compact dimensions due to use of surface mounting devices (SMT) and stateof-the-art power transistors (IGBT)
- Convenient commissioning via motion control module
- Rapid motor acceleration, deceleration, and reversing by momentary current increase to twice the rated current
- No noise due to switching frequency far above the audible range
- Servo power module protected by rapid discharge of DC-bus voltage in case of mains switch-off, frequent switch-on and -off possible without delay
- Simple fault diagnosis via motion control module and on site via LEDs

Characteristics of the motion control modules

- Highest accuracy due to digital position and speed control with motion coordination
- Integrated in the SYSTEM-90E controller system by Promicon Systems (19" plug-in module)
- Highest flexibility and dynamics due to multi-tasking operation and minimum response times
- Suitable for various position sensor types such as
 - resolvers
 - incremental encoders with RS422 signals
 - high-resolution incremental encoders with sine and cosine signals
 - EnDat (absolute encoders)
 - HIPERFACE (absolute encoders)
- Connection to TrioDrive C or MidiDrive C servo power modules via uniform pLINK interface

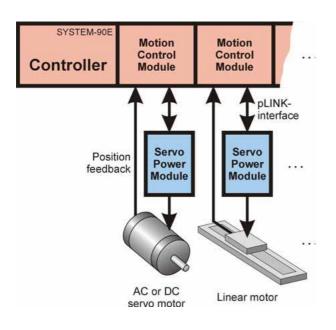
Overview of the Multi-Axis Servo System

Modular design

With the modular design of the multi-axis servo system, customized drive tasks can be carried out with a minimum number of components. For each axis, one servo power module and one motion control module are needed. The motor power determines the required servo power module, the motion control module is selected according to the desired position sensor system. The open system permits connection of any type of servo motors with a wide range of position feedback systems (see page 5). Being part of the Promicon SYSTEM-90E controller, the multi-axis servo system can use all its functions and, depending on the application, be extended with position controllers, digital and analog inputs and outputs, or field bus interfaces.

Flexible axis coordination

The multi-axis servo system provides all options of co-ordinated multi-axis motion. For that, SYS-TEM-90E offers a multi-tasking environment for up to 3 independent application programs. Minimum response times result in highest dynamics. As the software is not coupled with the axis motion and continues running while the axes carry out the drive task in the background, an extraordinary degree of freedom in the realization of automation tasks is guaranteed.



Digital parameterization

All axes are parameterized in SYSTEM-90E with only one software. This reduces the parameterization works. Furthermore, digital parameterization guarantees an absolute reproducibility of all settings.

Protection and monitoring functions

SYSTEM-90E offers extensive protection and monitoring functions from alarm to log file recording. The servo power modules are integrated into system diagnosis via the pLINK interface.

In case of a mains switch-off, a rapid discharge circuit is activated in the servo power modules to reduce the DC-bus voltage within less than 0.5 seconds. Thus, the drive is no longer able to carry out dangerous motions actively.

Servo Power Modules

General

The servo power modules supply energy to the motor. Depending on the required power, various types are available:

- TrioDrive C (up to approx. 1.8 kW motor power) rated current 2 to 6 A, mains connection 230 V AC
- MidiDrive C (up to approx. 11 kW motor power) rated current 2 to 20 A, mains connection 3 × 400/ 480 V AC

Design

The servo power modules are compact devices for installation in control cabinets. All connectors are located at the front panel. To avoid radiated emissions, the enclosure is made of zinc-plated sheet metal. Since the enclosure is not varnished, all metal parts have best electrical contact.

Mains connection

The power supply unit is integrated. The power component is fed directly by the mains (230 V AC or 3 × 400/480 V AC). For the control unit, a control supply voltage of 24 V has to be supplied. The power supply unit contains a RFI filter as well as a shunt regulator. The shunt resistor of this regulator absorbs the energy fed back when the motor is braked.

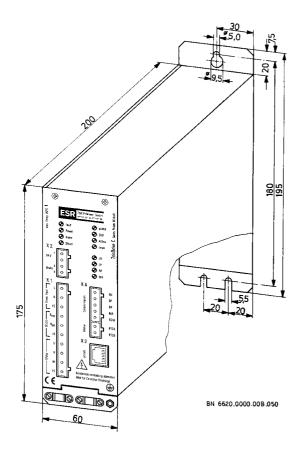


Figure 1: Dimensions TrioDrive C (mm)

Motor connection

Any type of servo motor can be connected to the servo power module: AC or DC servo motors, direct drives such as linear motors, torque motors, or solenoid motors, 2- and 3-phase servo motors with 1 to 50 pole pairs. The motor type is specified via the parameterization. The power supply cable is connected to the servo power module, the position sensor is connected to the motion control module.

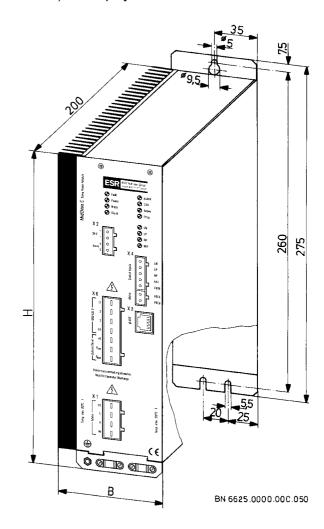
Interfaces of the servo power modules

All connections are plugged in at the front. This allows a specially easy, clear, and low-cost wiring:

- motor, mains connection, and external shunt resistor (if required)
- control supply voltage (24 V DC), brake (if installed)

- pLINK interface for the connection to the motion control module (RJ45)
- · control signals
- · motor temperature sensor

The operating mode of the servo power modules and the status of external signals (e. g. limit switch) are displayed via LEDs.



| Order Number | В | Н | |
|---------------------------|-----|-----|--|
| BN 6626, BN 6627, BN 6628 | 85 | 255 | |
| BN 6629, BN 6630 | 150 | 270 | |

Figure 2: Dimensions MidiDrive C (mm)

Motion Control Modules

General

The motion control modules are part of the Promicon SYSTEM-90E modular controller system. For integrated position and speed control, the motor position sensor is connected directly to the corresponding motion control module. The motor position sensor does not need to be connected to the servo power module which facilitates wiring. Different motion control modules are available for different position feedback systems.

Each motion control module is equipped with a quick-response setpoint generator creating a sequence of time-equidistant high-resolution interpolation points with a high resolution from the data of the driving task (target position, velocity, acceleration, and jerk).

Together with the high-precision jerk control, a particularly harmonic motion profile is created which protects the mechanical elements perfectly.

A special feature is that a motion can be started within a millisecond without delay.

Furthermore, velocity and target position can be modified during a running motion.

Position feedback systems

• Motion Control Module MCQ-5

for incremental encoders with square-wave signals Incremental encoders are inexpensive, and a wide range of motors equipped with them as standard is available.

Motion Control Module MCR-6

for common resolvers

The advantages of the resolver are a relatively small construction and a very low price. It stands out for a high control quality due to the flash evaluation without delay.

Motion Control Module MCS-7

for position sensors with sinusoidal incremental signals (Sincos encoders)

With the interpolation electronics of the motion control module, a sinus period can be resolved to up to 200 measurement steps which permits high-precision control.

Motion Control Module MCE-8

for absolute encoders with EnDat 2.1 interface With the interpolation electronics of the motion control module, a sinus period can be resolved to up to 200 measurement steps which permits high-precision control. Due to the evaluation of the sinus signals, the position information of the position sensor is improved, and a high-resolution absolute position information is created.

Motion Control Module MCE-9

for absolute encoders with digital EnDat 2.2 interface

The runtime compensation installed in the motion control module provides for a high transmission speed even with high cable lengths. This results in minimum position transmission times leading to a control with highest dynamics. The absolute position information is transmitted to the motion control module as purely digital signal which reduces the wiring.

Motion Control Module MCB-10

for absolute encoders with BiSS interface

This motion control module can be combined with a wide range of position sensor types with absolute position measurement. The controller automatically adjusts to the encoder so that a time-consuming parameterization is not required and motors and drives can be commissioned quickly. The runtime compensation installed in the motion control module provides for a high transmission speed even with high cable lengths. This results in minimum position transmission times leading to a control with highest dynamics. The absolute position information is transmitted as purely digital signal to the motion control module which reduces the wiring.

Interfaces of the motion control modules

All connections can be plugged in at the front. This allows a specially easy, clear, and low-cost wiring. The front panel also includes LEDs for simple diagnosis.

The following connectors are located at the front panel:

- motor position sensor (D sub connector)
- pLINK interface as connection to the servo power module (RJ45)

Accessories

| Description | Order Number | |
|---|--------------|--|
| Connector set for TrioDrive C servo power modules | ST 6620 | |
| Connector set for MidiDrive C servo power modules | ST 6625 | |
| Motor supply cable (power), 4 × 1.5 mm², shield | BN 8817* | |
| Motor supply cable for motor with brake, 4 × 1.5 mm² + 2 × 1 mm², shield | BN 8820* | |
| Motor choke for TrioDrive C with medium cable lengths (15 to 25 m) | BN 3845.2258 | |
| Motor choke for TrioDrive C with higher cable lengths (25 to 40 m) | BN 3857.2311 | |
| Resolver connection cable | BN 8818* | |
| Encoder connection cable (for incremental encoder with RS422 signals or Sincos encoder) | BN 8821* | |
| Encoder connection cable (for high-resolution incremental encoder or EnDat encoder) | BN 8829* | |
| External shunt resistor, 33 Ω, 600 W (in enclosure) (for TrioDrive C only) | EW 0600.0033 | |
| External shunt resistor, 68 Ω, 600 W (in enclosure) | EW 0600.0068 | |
| pLINK connection cable (standard patch cable CAT5) | on request | |

^{*} also available as ready-assembled cables

Order Numbers and Technical Specifications

TrioDrive C and MidiDrive C servo power modules

| Description | Order No. | |
|---|------------------------------------|---------|
| TrioDrive C | output current 2 A _{rms} | BN 6621 |
| 230 V mains connection, single-phase, corresponds to 320 V DC-bus | output current 4 A _{rms} | BN 6622 |
| | output current 6 A _{rms} | BN 6623 |
| MidiDrive C 3 × 400/480 V mains connection, corresponds to 560/680 V DC-bus | output current 2 A _{rms} | BN 6626 |
| | output current 4 A _{rms} | BN 6627 |
| | output current 8 A _{rms} | BN 6628 |
| | output current 12 A _{rms} | BN 6629 |
| | output current 20 A _{rms} | BN 6630 |

TrioDrive C and MidiDrive C servo power modules, major technical specifications

| Order Number Servo Power Module | BN 6621 | BN 6622 | BN 6623* | BN 6626 | BN 6627 | BN 6628 | BN 6629 | BN 6630 | |
|---|--|-------------|---------------------|--|-------------|-------------|---------|---------|--|
| Rated supply voltage | 230 V AC ±10%, 50 60 Hz | | | 3 × 400 480 V AC ±10%, 50 60 Hz | | | | | |
| Rated DC-bus voltage | 320 V DC | | | 560 680 V DC | | | | | |
| Permissible supply voltage | 42 253 V AC (corresponds to 60 360 V DC-bus voltage) | | | 85 528 V AC (corresponds to 120 740 V DC-bus voltage) | | | | | |
| Maximum mains inrush peak current | 5 A (at 230 V) | | | approx. 8.5 A (3 × 400 V) 10 A (3 × 480 V) | | | | 180 V) | |
| Rated current (rms) | 2 A | 4 A | 6 A | 2 A | 4 A | 8 A | 12 A | 20 A | |
| Maximum peak current (crest value) | 5.5 A | 11 A | 17 A | 5.5 A | 11 A | 22 A | 34 A | 55 A | |
| Switching frequency of the power circuit (can be parameterized) | 16 or 32 kHz | | 16 or 32 kHz 16 kHz | | 16 kHz | 8 or 16 kHz | | | |
| Power dissipation under rated conditions and at a switching frequency of 16 kHz | 30 W | 40 W | 50 W | 60 W | 100 W | 150 W | 200 W | 250 W | |
| Apparent electric power | 0.75 kVA | 1.5 kVA | 2.25 kVA | 1.3 kVA | 2.6 kVA | 5.2 kVA | 7.8 kVA | 13 kVA | |
| Max. possible motor power | 0.6 kW | 1.2 kW | 1.8 kW | 1.1 kW | 2.2 kW | 4.5 kW | 6.6 kW | 11 kW | |
| Max. continuous braking power (in- ternal) | 40 W | | | 50 W | | | 125 W | | |
| Pulse braking power, 1.5% ED, 1 s | | 2.1 kW | | | 8.2 kW | | 17 kW | | |
| Suitable shunt resistor (external) | 27120 Ω | 27100 Ω | 2770 Ω | 62220 Ω 62120 Ω 6270 Ω 3050 | | | | 50 Ω | |
| Control supply voltage | | | | 24 V D | C ±25% | | | | |
| Max. interruption time without power module reset | | | | 10 | ms | | | | |
| Current consumption at 24 V | ар | prox. 500 r | mΑ | ар | prox. 600 r | nA | approx. | 700 mA | |
| Max. length of motor connection cable | 15 m / 40 m (without / with choke) | | | 25 m | | | | | |
| Width | 60 mm | | | 85 mm | | | 150 mm | | |
| Height (without mounting straps) | 175 mm | | | 255 mm | | | 270 mm | | |
| Height (with mounting straps) | 195 mm | | | 275 mm | | | 305 mm | | |
| Depth without connector | 200 mm | | | | | | | | |
| Weight | 2.0 kg 3.4 kg 7.2 kg | | | | | kg | | | |
| Protection type | IP20 according to EN 60529 | | | | | | | | |
| Mounting height (without current reduction) | ≤ 1000 m above sea level | | | | | | | | |
| Mounting height (with current reduction) | ≤ 2000 m above sea level (–1.5% per 100 m above 1000 m) | | | | | | | | |
| Climatic category acc. to DIN EN 50178 | operation: 3K3 / storage: 1K4 / transportation: 2K3 | | | | | | | | |
| Permissible ambient temperature | +5 +40 °C / −25 +55 °C / −25 +70 °C | | | | | | | | |
| Permissible relative humidity | 5 85% / 5 95% / 5 95% | | | | | | | | |
| Compliance with EMC limits | first and second environment according to EN 61800-3 ** | | | | | | | | |

^{*} Power module BN 6623 (6 A device) may be operated up to a loading of 70% without restrictions. For a higher loading, the device must be installed next to a control cabinet fan or equipped with a sub-assembled fan.

^{**} This is a product with limited availability according to EN 61800-3. Operation of this device can cause radio interferences in the residential environment ("first environment") which might require appropriate action. In this case, please contact us.

Motion control modules and other modules of Promicon SYSTEM-90E (selection)

| Description | Order No. | |
|--|---------------|--|
| Basic devices with 24 V DC power supply and 5, 9, or 19 slots | PP SBR-5/9/19 | |
| Central units with VLRISC processor, 24 90 MHz, 16/32 bit, RS232 interface | PP CPU | |
| Motion control module for incremental encoders (RS422, 5.0 MHz) | PP MCQ-5 | |
| Motion control module for resolvers | PP MCR-6 | |
| Motion control module for high-res. incremental encoders with sine-cosine signals | PP MCS-7 | |
| Motion control module for EnDat 2.1 encoders (absolute encoder) | PP MCE-8 | |
| Motion control module for EnDat 2.2 encoders (absolute encoder) | PP MCE-9 | |
| Motion control module for EnDat encoders with BiSS interface | PP MCE-10 | |
| Position controller* for incremental encoders (12 bit DAC, 250 kHz or 16 bit DAC, 2.0 MHz) | PP PCQ-3/-4 | |
| Position controller* for absolute encoders (16 bit DAC, SSI interface) | PP PCS-4 | |
| RS232 interface double, 115 kBaud | PP SDC-3 | |
| Profibus DP interface up to 32 byte | PP PBS-1 | |
| Interbus interface double conductor remote bus or peripheral bus | PP IBS-3/-2 | |
| 16 digital inputs, 24 V (optocoupler) | PP DI-7 | |
| 16 digital outputs, 24 V (optocoupler) | PP DO-8 | |
| 8 digital inputs, 8 digital outputs 24 V (optocoupler) | PP DIO-6 | |
| 2 analog inputs, 2 analog outputs 12 Bit | PP VIO-2 | |
| Operating panel with 26 × 12 characters, 35 keys, 10 of them function keys with LED | PP PT-1226 | |
| Software for operation and programming | PP PIDS | |
| OPC server via pNET online communication | PP POPC | |

^{*} with ±10 V output for speed setpoint, e. g. for connecting the TrioDrive A or MidiDrive A analog servo drives.

Drive System Packages

On the basis of the modular multi-axis system with TrioDrive C and MidiDrive C servo power modules, the motion control modules, and our AC, DC, or linear motors, we will be pleased to select drive and control packages according to your specifications. Information on the servo motors can be found in the following data sheets:

- MR 4 AC Servo Motors (Data Sheet 6660.260)
- MR 77 AC Servo Motors (Data Sheet 6677.260)
- MR 6 AC Servo Motors (Data Sheet 6612.264)
- RS/RX DC Servo Motors (Data Sheet 6508.260)
- MR 74 AC Servo Motors (Data Sheet 6674.260)
- ML 1 Linear Motors (Data Sheet 6700.261)

We will be pleased to determine the servo drive matching your application and submit you an offer.

The statements in this data sheet are for information, only. They do not guarantee properties. We reserve the right to make changes without notice.

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